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1) let p = Array.make 21 (1,3);;
   for i = 1 to 20 do
     let (x, y) = p.(i-1) in
     p.(i) <- x * 17 mod 23, y * 17 mod 19
   done;;

2) let alpha (a:point) (b:point) (c:point) =
   (fst b - fst a)*(snd c - snd a) -
   (fst c - fst a)*(snd b - snd a)
   ;;

print_newline ();
for i = 2 to 20 do
  for j = 1 to i-1 do
    for k = 0 to j-1 do
      if alpha p.(i) p.(j) p.(k) = 0
      then begin
        print_string "alignement ";
        print_int k;
        print_string " ";
        print_int j;
        print_string " ";
        print_int i;
        print_newline () end
      done
    done
  done;;

3) let plus_bas (p : point array) =
   let n = Array.length p in
   let a = ref p.(0) in
   for j = 1 to n-1 do
     if (snd !a > snd p.(j))
       || (snd !a = snd p.(j) && fst !a > fst p.(j))
     then a := p.(j)
   done;
   !a
   ;;

let plus_haut (p : point array) =
   let n = Array.length p in
   let a = ref p.(0) in
   for j = 1 to n-1 do
     if (snd !a < snd p.(j))
       || (snd !a = snd p.(j) && fst !a < fst p.(j))
     then a := p.(j)
   done;

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 !a
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4) let rec plus_a_droite b h (l : point list) = match l with
 | [] -> b, []
 | t::q ->
 let m, d = plus_a_droite b h q in
 let a = alpha b t h in
 if a <= 0 then m, d
 else match d with
 | [] -> t, [t]
 | _ -> if a > alpha b m h
 then t, t::d
 else m, t::d
 ;;
5) On ne met pas le point final pour éviter d'avoir des doublons.
 let rec quickHull_drte b h (l : point list) =
 match plus_a_droite b h l with
 | _, [] -> [b]
 | m, d -> (quickHull_drte b m d)@(quickHull_drte m h d)
 ;;
6) let quickHull (p : point array) =
 let b = plus_haut p in
 let h = plus_bas p in
 let l = Array.to_list p in
 (quickHull_drte b h l)@(quickHull_drte h b l)
7) let rec nb_inv_tete x l = match l with
 | [] -> 0
 | t :: q when x > t -> 1 + nb_inv_tete x q
 | t :: q -> nb_inv_tete x q;;
8) let rec nb_inv liste =
 match liste with
 | [] -> 0
 | h :: tl -> nb_inv_tete h tl + nb_inv tl
 ;;
9) a) Ces deux nombres sont égaux.
 b) Le nombre d'inversions dans l est la somme de ces trois nombres.
10) let rec scinde_stable l i =
 if i = 0 then [], l
 else let t :: q = l in
 let q1, q2 = scinde_stable q (i-1) in
 t::q1, q2;;
11) let nb_inv_fus liste =

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let cpt = ref 0 in
let rec fusion l1 l2 = match l1,l2 with
 | [],_ -> l2
 | _,[] -> l1
 | x1::q1,x2::q2 when x1<x2 -> x1::(fusion q1 l2)
 | _,x2::q2 -> cpt := !cpt + List.length l1; x2::(fusion l1 q2)
in
let rec tri l = match l with
 | [] -> []
 | [x] -> [x]
 | _ -> let l1,l2 = scinde_stable l (List.length l/2) in
 fusion (tri l1) (tri l2)
in ignore(tri liste); !cpt;;

12) #load "graphics.cma";;
open Graphics;;
open_graph "";

13) let trace_point (a : point) =
 let h = min (size_x () / 23) (size_y () / 19) in
 fill_circle (h * fst a) (h * snd a) 3
;;

let ecrit (a : point) chaine =
 let h = min (size_x () / 23) (size_y () / 19) in
 moveto (h * fst a) (h * snd a);
 draw_string chaine
;;

(* Trace le nuage de points *)
clear_graph ();
for i = 0 to 20 do
 trace_point p.(i);
 moveto (fst p.(i)) (snd p.(i));
 ecrit p.(i) (string_of_int i)
done;;

14) let h = min (size_x () / 23) (size_y () / 19) in
 let dilate m = (h * fst m, h * snd m) in
 let qh = quickHull p in
 draw_poly_line (Array.of_list
 (List.map dilate (qh@[List.hd qh])));;

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